

# Standard Interface for Robotic Manipulation



## Overview

SIROM by Sener is a modular plug-and-play Standard Interface for in-orbit satellite servicing. The family product line consists of multifunctional interfaces combining:

- **Mechanical** interface for capture and hard docking.
- **Electrical** interface for power transmission.
- **Data** interfaces for high-rate data transfer.
- Optionally, a **resupply** interface for refuelling or heat regulation.

Most SIROM families are available in three basic configurations: Active, Passive, and Active-Passive (which can mate with any other). The characteristics in terms of mass, volume and cost vary among them, allowing **optimization of system design**.

## Features

SIROM is designed as an **androgynous** interface allowing easy mating/demating with other SIROMs. Its **high capture-range latches** combined with its **guiding petals**, provide SIROM a self-aligning capability tolerant to very large misalignment conditions. The docking system keeps the locked position without the need of friction brakes or power consumption. Also, SIROM features a **capture switch** independent of illumination conditions, that gives information once two SIROMs are within the latching capture range. Once mechanically latched, SIROM deploys its connectors board to establish a physical plug for data, electrical power transmission or fluid transmission. The available lines are:

- **CAN bus** control lines (main and redundant)
- **High-speed data** transmission lines, customizable (Gigabit Ethernet, SpaceWire...)
- **Power transfer (28V)** used for SIROM power supply.
- **High-power transfer** that bypasses SIROM electronics.
- **Resupply interface** (based on RIDER connector) allowing transfer of propellant (Xenon, Hydrazine, etc.) or coolant.

## Customization

Within each family line, SIROM allows customization of:

- Data protocols and electrical power transfer.
- Active, Passive, or Active-Passive versions.
- Integrated electronics or distributed modular electronics.
- Configurable power supply rails.
- Visual servoing system (marker based).



*Robot manipulator provided with SIROM as end effector handling a mirror tile.*



*Two SIROMs during docking.*

## Applications

- On-orbit servicing, Refuelling, Resupply.
- In-orbit assembly.
- Assembly of large structures in space.
- Payload upgrade or replacement for satellites (refurbishment).
- Robot tool exchange.
- De-orbiting.
- Active debris removal

*ELECTRICAL version for ground demonstrations*



*ELECTRICAL version for flight applications (on-going)*



*ELECTRICAL and FLUIDIC versions for flight applications (on-going)*



## GENERAL INFORMATION

	SIROM C	SIROM E	SIROM G
<b>Size (ø x h)</b>	X: 145 x 132 mm P: 145 x 73 mm	X: 145 x 122.5 mm P: 145 x 69.5 mm	A: 145 x 124.7 mm P: 145 x 109 mm
<b>Mass</b>	X: 1.1 kg P: 0.4 kg	X: 1.85 kg P: 0.632 kg	A: 1.631 kg + 0.685 kg (electronics) P: 1.389 kg
<b>Capture range before contact</b>	Axial: +15 mm Radial: +/-5 mm	Axial: +13.5 mm Radial: +/-6 mm	Axial: +13.5 mm Radial: +/-6 mm
<b>Docking time</b>	5 s	1-7 s	1-7 s
<b>TRL</b>	6	4 (Expected 6 in Q4 2026)	4 (Expected 6 in Q4 2026)
<b>Projects</b>	MIRROR, ISAAC, EU-RISE	EROSS-IOD, ORU-BOAS, InSPoC-1	EROSS-IOD, EROSS-SC

## MECHANICAL PERFORMANCE<sup>1</sup>

<b>Traction load</b>	1,3 kN	3 kN   4.8 kN <sup>2</sup>	3 kN
<b>Compression load</b>	5 kN	3 kN	3 kN
<b>Radial load</b>	5 kN	3 kN	3 kN
<b>Torque</b>	220 Nm	200 Nm   320 Nm	200 Nm
<b>Bending moment</b>	150 Nm	140 Nm   280 Nm	140 Nm

<sup>1</sup> Mechanical tests performed for SIROM E and G Active-Passive configuration.

<sup>2</sup> Load estimated for single and double latching scenario. Note that double latching is exclusively possible with androgynous interfaces.

## ELECTRICAL PERFORMANCE

	SIROM C	SIROM E	SIROM G
<b>Integrated electronics</b>	Yes	Optional	No
<b>Power consumption</b>	Stand-by: 3 W Active mode: 10 W	Stand-by: 2.5W Active mode: 9.5 W	Stand-by: 2.5 W Active mode: 18.5 W
<b>Power input</b>	20-34V (nominal 28V) DC/DC isolation	Nominal 28V 5, 15, 30V optional	Nominal 28V 5, 15, 30V optional
<b>Power Transfer: a) regulated b) by-pass</b>	a) 3.5A @ 28V (98 W) b) 15A @ 100V (1.5 kW)	a) 3.5A @ 28V (98 W) b) 10A @ 75V (750W)	a) 3.5A @ 28V (98W) b) 10A @ 75V (750W)
<b>Data Transfer</b>	Gigabit Ethernet or similar	Gigabit Ethernet or similar	Gigabit Ethernet or similar
<b>Connectors plate</b>	132 POGO pins/pads	48 POGO pins/pads	48 POGO pins/pads
<b>ESD cover</b>	No	Yes	Yes
<b>Radiation tolerant</b>	No	Yes (LEO missions)	Yes (LEO missions)

## REFUELLING INFORMATION

<b>Resupply</b>	-	-	Fluid transfer connector (coolant/propellant compatible)
<b>MEOP</b>	-	-	150bar
<b>Flow rate</b>	-	-	Gas (He): 5g/s @ 1bar $\Delta p$ Liquid (Water): 10g/s @ 1bar $\Delta p$